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Periodic solution for a delay integro-differential equation in biomathematics

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Abstract

Sufficient conditions for the existence and uniqueness of periodic solution of a delay integro-differential equation which arise in biomathematics are given. The results use a bidimensional variant of the Perov's fixed point theorem.

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1 Introduction

In this paper we consider a model for the spread of certain infections disease with a contact rate that varies seasonally. This model is govern by the following integro-differential equation

$$x(t) = \int_{t-\tau}^{t} f(s, x(s), x'(s)) ds$$
 (1)

where:

(i) x(t) is the proportion of infectious in population at time t;

(ii) $\tau > 0$ is the length of time in which an individual remains infectious;

(iii) x'(t) is the speed of infectivity;

(iv) f(t, x(t), x'(t)) is the proportion of new infections on unit time.

We study the existence and uniqueness of a positive and periodic solution for equation (1).

A similary integral equation which models the same problem

$$x(t) = \int_{t-\tau}^{t} f(s, x(s)) ds$$
(2)

has been considered in [4], [5], [9], [8], [13] and [10] where sufficient conditions for the existence of nontrivial periodic nonnegative and continous solutions for this equation are given in the case of a periodic contact rate: $f(t + \omega, x) = f(t, x)$, $\forall t \in \mathbb{R}$. The tools were: Banach fixed point principle in [10], topological fixed point theorems in [4], [5], [8], [13], fixed point index theory in [5] and monotone technique in [5], [8], [9]. Also, a system of integral equations in the form (2) has been studied in [2] and [11] using: the monotone technique in [2] and the Perov's fixed point theorem for differentiable dependence by the parameter of the solution in [11]. In [1], sufficient conditions for the existence and uniqueness of a positive, continuous solution of the following initial value problem

$$x(t) = \begin{cases} \int_{t-\tau}^{t} f(s, x(s), x'(s)) \, ds, & t \in [0, T] \\ \varphi(t), & t \in [-\tau, 0] \end{cases}$$

are obtained.

In the following, if X is a nonempty set then by a generalized metric d on X we understand a function $d: X \times X \to \mathbb{R}^n$ which fulfils the following:

$$\begin{array}{l} 0_{\mathbb{R}^{n}} \leq d\left(x,y\right), \forall x,y \in X \text{ and } d\left(x,y\right) = 0_{\mathbb{R}^{n}} \Leftrightarrow x = y \\ d\left(x,y\right) = d\left(y,x\right), \forall x,y \in X \\ d\left(x,y\right) \leq d\left(x,z\right) + d\left(z,y\right), \forall x,y,z \in X, \end{array}$$

where for $x = (x_1, x_2, ..., x_n)$ and $y = (y_1, y_2, ..., y_n)$ from \mathbb{R}^n we have $x \leq y \Leftrightarrow x_i \leq y_i$, for any $i = \overline{1, n}$. The pair (X, d) will be called generalized metric space.

2 Existence and uniqueness

We suppose that $f \in C(\mathbb{R} \times \mathbb{R}_+ \times \mathbb{R})$ and exists $\varpi > 0$ such that

$$f(t + \varpi, x, y) = f(t, x, y), \ \forall (t, x, y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

We consider the following functional spaces

$$\begin{split} X(\varpi) &= \{ y \in C(\mathbb{R}) : y(t + \varpi) = y(t), \ \forall t \in \mathbb{R} \} \\ X_1(\varpi) &= \{ x \in C^1(\mathbb{R}) : x(t + \varpi) = x(t), \ \forall t \in \mathbb{R} \} \\ X_+(\varpi) &= \{ x \in X_1(\varpi) : x(t) \ge 0, \ \forall t \in \mathbb{R} \}. \end{split}$$

and denote by X the product space $X = X_+(\varpi) \times X(\varpi)$ which is generalized metric space with

$$d_C: X \times X \to \mathbb{R}^2, \, d_C\left((x_1, y_1), (x_2, y_2)\right) = \left(\|x_1 - x_2\|, \|y_1 - y_2\|\right),$$

where

$$||u|| = \max\{|u(t)| : t \in [0, \varpi]\}$$

for any $u \in X(\varpi)$.

.To obtain the existence and uniqueness result for the integro-differential equation (1) we use the following Perov's fixed point theorem [7] (see also [3], [6])

Theorem 1 (Perov, see [7]) Let (X, d) a complete generalized metric space with $d(x, y) \in \mathbb{R}^n$. If $T : X \to X$ is a map for which exists a matrix $A \in \mathcal{M}_n(\mathbb{R})$ such that

$$d\left(T\left(x\right),T\left(y\right)\right) \leq Ad\left(x,y\right), \forall x,y \in X$$

and the eigenvalues of A lies in the open unit disc from \mathbb{R}^2 , then T has a unique fixed point x^* and the sequence of successive approximations $x_m = T^m(x_0)$ converges to x^* for any $x_0 \in X$. Moreover, the following estimation holds

$$d(x_m, x^*) \le A^m (I_2 - A)^{-1} d(x_0, x_1), \forall m \in \mathbb{N}^*.$$

If we derive (1) with respect t and denoting y(t) = x'(t) we obtain

$$y\left(t\right) = f\left(t, x\left(t\right), y\left(t\right)\right) - f\left(t - \tau, x\left(t - \tau\right), y\left(t - \tau\right)\right), \ \forall t \in \mathbb{R}$$

which lead to

$$x(t) = \int_{t-\tau}^{t} f(s, x(s), y(s)) ds$$

$$y(t) = f(t, x(t), y(t)) - f(t - \tau, x(t - \tau), y(t - \tau))$$
(3)

Let $T: X \to C(\mathbb{R}) \times C(\mathbb{R})$ the map given by

$$T(x,y) = (T_1(x,y), T_2(x,y))$$

$$\begin{pmatrix} T_1(x,y)(t) \\ T_2(x,y)(t) \end{pmatrix} = \begin{pmatrix} \int_{t-\tau}^{t} f(s,x(s),y(s)) \, ds \\ f(t,x(t),y(t)) - f(t-\tau,x(t-\tau),y(t-\tau)) \end{pmatrix}$$
(4)

We impose the following conditions:

(i) $f \in C(\mathbb{R} \times \mathbb{R}_+ \times \mathbb{R})$ and exists $m, M \ge 0$ such that

$$m \leq f(t, x, y) \leq M, \ \forall (t, x, y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

(ii) f has the property

$$f(t+\varpi,x,y) = f(t,x,y), \ \forall (t,x,y) \in \mathbb{R} \times \mathbb{R}_+ \times \mathbb{R}.$$

(iii) exists $\alpha, \beta > 0$ such that

$$|f(t, u, v) - f(t, u', v')| \le \alpha |u - u'| + \beta |v - v'|$$

 $\forall t \in \mathbb{R}, \forall u, u' \in \mathbb{R}_+, \forall v, v' \in \mathbb{R}.$

From condition (i) we see that $T_1(X) \subseteq C^1(\mathbb{R})$ and

$$T_{1}(x,y)(t) = \int_{t-\tau}^{t} f(s, x(s), y(s)) \, ds \ge \int_{t-\tau}^{t} m ds = m\tau$$

 $\forall t \in \mathbb{R}$. It is obvious that $T_1(x, y)(t) \leq M\tau \ \forall t \in \mathbb{R}, \forall (x, y) \in X$.

Theorem 2 If the conditions (i)-(iii) are satisfied and $\alpha \tau + 2\beta < 1$ then the integro-differential equation (1) have in $X_+(\varpi)$ an unique solution.

Proof. From condition (ii) follows that $T_1(X) \subset X_+(\varpi)$. Indeed,

$$T_1(x,y)(t+\varpi) = \int_{t+\varpi-\tau}^{t+\varpi} f(s,x(s),y(s)) \, ds =$$
$$= \int_{t-\tau}^t f(u-\varpi,x(u-\varpi),y(u-\varpi)) \, du =$$
$$= \int_{t-\tau}^t f(u-\varpi+\varpi,x(u-\varpi+\varpi),y(u-\varpi+\varpi)) \, du =$$
$$= T_1(x,y)(t), \ \forall t \in \mathbb{R}, \forall (x,y) \in X.$$

In addition

$$T_{2}(x,y)(t+\varpi) = f(t+\varpi, x(t+\varpi), y(t+\varpi)) - -f(t+\varpi-\tau, x(t+\varpi-\tau), y(t+\varpi-\tau)) =$$

$$= f(t+\varpi, x(t), y(t)) - f(t+\varpi-\tau, x(t-\tau), y(t-\tau))$$

$$= f(t, x(t), y(t)) - f(t-\tau, x(t-\tau), y(t-\tau)) = T_{2}(x, y)(t)$$

 $\forall t \in \mathbb{R}, \forall (x, y) \in X.$ Consequently, $T(X) \subset X.$ Let $(x_1, y_1), (x_2, y_2) \in X.$

$$|T_{1}(x_{1}, y_{1})(t) - T_{1}(x_{2}, y_{2})(t)| =$$

$$= \left| \int_{t-\tau}^{t} f(s, x_{1}(s), y_{1}(s)) ds - \int_{t-\tau}^{t} f(s, x_{2}(s), y_{2}(s)) ds \right| \leq$$

$$\leq \int_{t-\tau}^{t} |f(s, x_{1}(s), y_{1}(s)) - f(s, x_{2}(s), y_{2}(s))| ds \leq$$

$$\leq \int_{t-\tau}^{t} [\alpha |x_{1}(s) - x_{2}(s)| + \beta |y_{1}(s) - y_{2}(s)|] ds \leq$$

$$\leq \alpha \tau ||x_{1} - x_{2}|| + \beta \tau ||y_{1} - y_{2}||, \forall t \in [0, \varpi].$$

and

$$\begin{split} |T_2(x_1, y_1)(t) - T_2(x_2, y_2)(t)| &= |f(t, x_1(t), y_1(t)) - \\ -f(t - \tau, x_1(t - \tau), y_1(t - \tau)) - f(t, x_2(t), y_2(t)) + \\ +f(t - \tau, x_2(t - \tau), y_2(t - \tau)) |&\leq |f(t, x_1(t), y_1(t)) - \\ -f(t, x_2(t), y_2(t)) | + |f(t - \tau, x_1(t - \tau), y_1(t - \tau)) \\ -f(t - \tau, x_2(t - \tau), y_2(t - \tau)) |&\leq \alpha |x_1(t) - x_2(t)| + \\ +\beta |y_1(t) - y_2(t)| + \alpha |x_1(t - \tau) - x_2(t - \tau)| + \\ +\beta |y_1(t - \tau) - y_2(t - \tau)| \leq 2\alpha ||x_1 - x_2|| + \\ +2\beta ||y_1 - y_2||, \forall t \in [0, \varpi], \forall (x_1, y_1), (x_2, y_2) \in X \end{split}$$

Then

$$\begin{pmatrix} \|T_1(x_1, y_1) - T_1(x_2, y_2)\| \\ \|T_2(x_1, y_1) - T_2(x_2, y_2)\| \end{pmatrix} \leq \\ \leq \begin{pmatrix} \alpha \tau \|x_1 - x_2\| + \beta \tau \|y_1 - y_2\| \\ 2\alpha \|x_1 - x_2\| + 2\beta \|y_1 - y_2\| \end{pmatrix} = \\ = \begin{pmatrix} \alpha \tau & \beta \tau \\ 2\alpha & 2\beta \end{pmatrix} \cdot \begin{pmatrix} \|x_1 - x_2\| \\ \|y_1 - y_2\| \end{pmatrix}$$

that is

$$d_C(T(x_1, y_1), T(x_2, y_2)) \le A \cdot d_C((x_1, y_1), (x_2, y_2))$$

The matrix

$$A = \begin{pmatrix} \alpha \tau & \beta \tau \\ 2\alpha & 2\beta \end{pmatrix}$$
(5)

has the eigenvalues $\lambda_1 = 0$ and $\lambda_2 = 2\beta + \alpha \tau$. Since $\alpha \tau + 2\beta < 1$, by the Perov's fixed point theorem we infer that T has in X an unique fixed point, denoted by $x_* = (x^*, y^*)$. It is easy to see that $(x^*)'(t) = y^*(t), \forall t \in \mathbb{R}$. Indeed,

$$y^{*}(t) = f(t, x^{*}(t), y^{*}(t)) - f(t - \tau, x^{*}(t - \tau), y^{*}(t - \tau))$$
$$x^{*}(t) = \int_{t-\tau}^{t} f(s, x^{*}(s), y^{*}(s)) ds$$

and after derivation,

$$(x^{*})'(t) = f(t, x^{*}(t), y^{*}(t)) - f(t - \tau, x^{*}(t - \tau), y^{*}(t - \tau))$$

Then, $x^* \in X_+(\varpi)$ is the solution of the equation (1).

From the above result, the solution x^* of (1) and his derivative are ϖ -periodic.

Theorem 3 In the conditions of Theorem 2 the solution x_* of (3), which is obtained by the successive approximations method starting from any $x^0 = (x_0, y_0) \in X$, verify the following estimation

$$d_C\left(x^m, x_*\right) \leq \frac{\lambda_2^{m-1}}{1-\lambda_2} \left(\begin{array}{cc} \alpha \tau & \beta \tau \\ 2\alpha & 2\beta \end{array}\right) d_C\left(x^1, x^0\right).$$

where $x^m = T(x^{m-1}), x^m = (x_m, y_m), \forall m \in \mathbb{N}^*.$

Proof. From Theorem 1, in conditions of Theorem 2 we have that

 $d_B(x^m, x^*) \le A^m (I - A)^{-1} d_B(x^1, x^0), \forall m \in \mathbb{N}^*.$

For the matrix A given in (5) we have $A^m = \lambda_2^{m-1} A$, $\forall m \in \mathbb{N}^*$ and $(I - A)^{-1} = \frac{1}{1 - \lambda_2} \begin{pmatrix} 1 - 2\beta & \beta\tau \\ 2\alpha & 1 - \alpha\tau \end{pmatrix}$.

The solution of (1) and his derivative can be obtained by the successive approximations method starting from any element of X.

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